

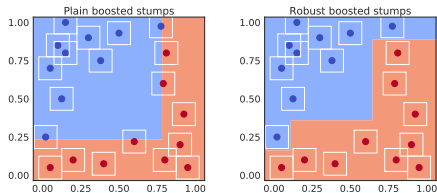
Provably Robust Boosted Decision Stumps and Trees against Adversarial Attacks

Maksym Andriushchenko (EPFL*)
Matthias Hein (University of Tübingen)

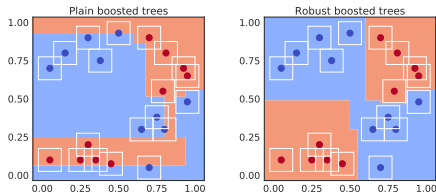
*Work done at the University of Tübingen

SMLD 2019, NeurIPS 2019

Stumps



Trees



Adversarial vulnerability

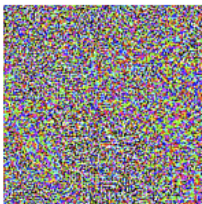


x

“panda”

57.7% confidence

+ .007 ×



$\text{sign}(\nabla_x J(\theta, x, y))$

“nematode”

8.2% confidence

=



$x +$

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99.3 % confidence

Source: Goodfellow et al, “Explaining and Harnessing Adversarial Examples”, 2014

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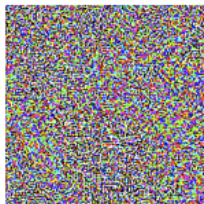


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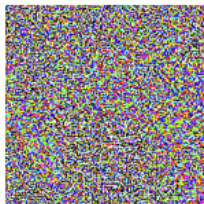


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- **Problem:** small changes in the input \Rightarrow large changes in the output
- Topic of active research for neural networks and image recognition, but what about **other domains** and **other classifiers**?

Motivation: other domains (going beyond images)

occupation	relationship	race	sex	capital-gain	capital-loss	hours-per-week	native-country	salary
NaN	Wife	White	Female	0	1902	40	United-States	>=50k
Exec-managerial	Not-in-family	White	Male	10520	0	45	United-States	>=50k
NaN	Unmarried	Black	Female	0	0	32	United-States	<50k
Prof-specialty	Husband	Asian-Pac-Islander	Male	0	0	40	United-States	>=50k
Other-service	Wife	Black	Female	0	0	50	United-States	<50k

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- For **high-stakes** decision making, it's **necessary** to ensure a reasonable worst-case error rate under *possible* noise perturbations
- The expected perturbation range can be specified by **domain experts**

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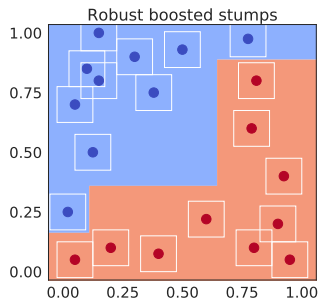
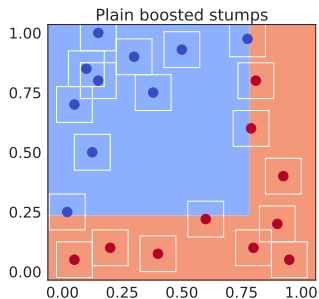
So why do adversarial examples exist?

Understanding adversarial vulnerability

- What goes **wrong** and how to fix it?

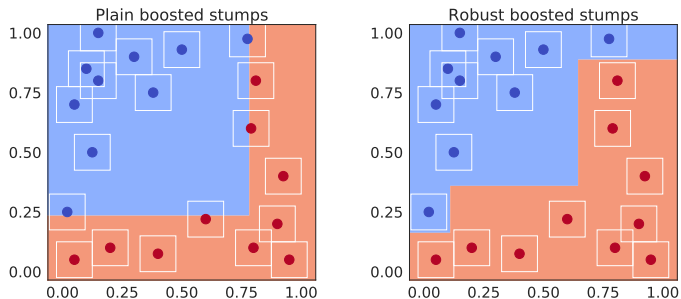
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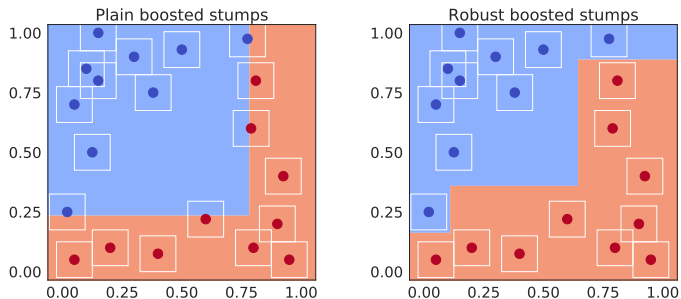
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Let's formalize the problem!

Adversarial robustness

- What is an **adversarial example**? Consider $x \in \mathbb{R}^d$, $y \in \{-1, 1\}$, classifier $f : \mathbb{R}^d \rightarrow \mathbb{R}$, some L_p -norm threshold ϵ :

$$\min_{\delta \in \mathbb{R}^d} yf(x + \delta)$$
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- How to measure robustness? **Robust test error (RTE)**:

$$\underbrace{\frac{1}{n} \sum_{i=1}^n \mathbb{1}_{yf(x) < 0}}_{\text{standard zero-one loss}} \quad \rightarrow \quad \underbrace{\frac{1}{n} \sum_{i=1}^n \mathbb{1}_{yf(x+\delta^*) < 0}}_{\text{robust zero-one loss}}$$

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- Finding δ^* : **non-convex** opt. problem for NNs and BTs. Exact **mixed integer formulations** exist for ReLU-NNs and BTs (**slow**).

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- **Provable defenses:** upper bound the robust loss
 \implies minimization of an upper bound on the objective

Robustness Certification and Robust Optimization for Boosted Trees

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- For a decision tree: $\min_{\|\delta\|_\infty \leq \epsilon} yu_{q_t(x+\delta)}^{(t)}$ can be found **exactly** by checking all leafs which are reachable in $B_\infty(x, \epsilon)$ ($O(l)$ time)

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- **Yes!** For monotonically decreasing L (e.g. exp. loss):

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- \implies we can calculate an upper bound on the **robust loss**.
- Now: come up with a proper update **for a new weak learner**.

- The robust loss for a tree ensemble can be **upper bounded** as

$$\begin{aligned} \max_{\|\delta\|_\infty \leq \epsilon} L(y_i F(x_i + \delta) + y_i f(x_i + \delta)) &= L\left(\min_{\|\delta\|_\infty \leq \epsilon} \left[\sum_{t=1}^T y_i f_t(x_i + \delta) + y_i f(x_i + \delta)\right]\right) \\ &\leq L\left(\sum_{t=1}^T \min_{\|\delta\|_\infty \leq \epsilon} y_i f_t(x_i + \delta) + \min_{\|\delta\|_\infty \leq \epsilon} y_i f(x_i + \delta)\right) = L\left(\tilde{G}(x_i, y_i) + \min_{\|\delta\|_\infty \leq \epsilon} y_i f(x_i + \delta)\right) \end{aligned}$$

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- For a **particular node** during the tree construction process, the **robust objective** is (I : set of points **reachable** for the current leaf):

$$\min_{w_l, w_r \in \mathbb{R}} \sum_{i \in I} L\left(\tilde{G}(x_i, y_i) + y_i w_l + \min_{|\delta_j| \leq \epsilon} y_i w_r \mathbb{1}_{x_{ij} + \delta_j \geq b}\right)$$

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- How to solve the **minimization problem**? Just a case distinction:

$$\min_{|\delta_j| \leq \epsilon} y_i w_r \mathbb{1}_{x_{ij} + \delta_j \geq b} = y_i w_r \cdot \begin{cases} 1 & \text{if } b - x_{ij} < -\epsilon \text{ or } (|b - x_{ij}| \leq \epsilon \text{ and } y_i w_r < 0) \\ 0 & \text{if } b - x_{ij} > \epsilon \text{ or } (|b - x_{ij}| \leq \epsilon \text{ and } y_i w_r \geq 0) \end{cases}$$

- Denoting the case distinction as $\mathbb{1}(x_i, y_i; w_r)$, our final robust objective is:

$$L^*(j, b) = \min_{w_l, w_r \in \mathbb{R}} \sum_{i \in I} L \left(\tilde{G}(x_i, y_i) + y_i w_l + y_i w_r \mathbb{1}(x_i, y_i; w_r) \right)$$

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- **Complexity**: $O(n^2)$, while XGBoost has $O(n \log n)$

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- **Complexity**: $O(n^2)$, while XGBoost has $O(n \log n)$

That's it for boosted trees

Now what is so special about boosted stumps (one-level trees)?

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- Moreover, we also derive an efficient update of the ensemble.
- \implies **interesting result** since previously exact certification and robust optimization was known only for linear classifiers

Experiments

Experiments

Dataset	# classes	# features	# train	# test	Reference
breast-cancer	2	10	546	137	Dua and Graff (2017)
diabetes	2	8	614	154	Smith et al. (1988)
cod-rna	2	8	59535	271617	Uzilov et al. (2006)
MNIST 1-5	2	784	12163	2027	LeCun (1998)
MNIST 2-6	2	784	11876	1990	LeCun (1998)
FMNIST shoes	2	784	12000	2000	Xiao et al. (2017)
GTS 100-rw	2	3072	4200	1380	Stallkamp et al. (2012)
GTS 30-70	2	3072	2940	930	Stallkamp et al. (2012)
MNIST	10	784	60000	10000	LeCun (1998)
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- We test our methods on various datasets, including some image classification datasets (to compare to the literature).
- However, our methods are primarily suitable for **tabular data**

Boosted trees: results

Dataset	$l_\infty \epsilon$	Normal trees (standard training)			Adv. trained trees (with cube attack)			Robust trees Chen et al. [9]		Our robust trees (robust loss bound)		
		TE	RTE	URTE	TE	RTE	URTE	TE	RTE	TE	RTE	URTE
breast-cancer	0.3	0.7	81.0	81.8	0.0	27.0	27.0	0.7	13.1	0.7	6.6	6.6
diabetes	0.05	22.7	55.2	61.7	26.6	46.8	46.8	22.1	40.3	27.3	35.7	35.7
cod-rna	0.025	3.4	37.6	47.1	10.9	24.8	24.8	10.2	24.2	6.9	21.3	21.4
MNIST 1-5	0.3	0.1	90.7	96.0	1.3	9.0	9.5	0.3	2.9	0.2	1.3	1.4
MNIST 2-6	0.3	0.4	89.6	100	2.3	15.1	15.9	0.5	6.9	0.7	3.8	4.1
FMNIST shoes	0.1	1.7	99.8	99.9	5.5	14.1	14.2	3.1	13.2	3.6	8.0	8.1
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- **Note:** upper bounds (URTE) are remarkably close to RTE!

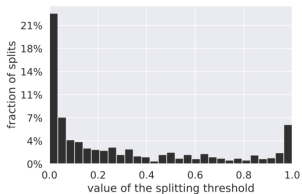
Multi-class comparison to provable defenses for CNNs

Dataset	$l_\infty \epsilon$	Approach	TE	LRTE	URTE
MNIST	0.3	Wong et al. [73]*	13.52%	26.16%	26.92%
		Xiao et al. [75]	2.67%	7.95%	19.32%
		Our robust trees, depth 30	2.68%	12.46%	12.46%
		Gowal et al. [25]	1.66%	6.12%	8.05%
FMNIST	0.1	Wong and Kolter [72]	21.73%	31.63%	34.53%
		Croce et al. [13]	14.50%	26.60%	30.70%
		Our robust trees, depth 30	14.15%	23.17%	23.17%
CIFAR-10	8/255	Xiao et al. [75]	59.55%	73.22%	79.73%
		Wong et al. [73]	71.33%	–	78.22%
		Our robust trees, depth 4	58.46%	74.69%	74.69%
		Dvijotham et al. [16]	59.38%	67.68%	70.79%
		Gowal et al. [25]	50.51%	65.23%	67.96%

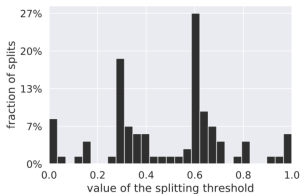
**We outperform almost all provable defenses for CNNs,
except one recent method (Gowal et al, 2018)!**

Distribution of splitting thresholds

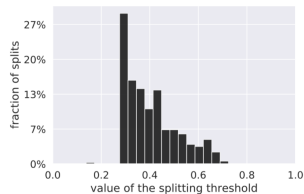
MNIST 2-6: plain trees



MNIST 2-6: adv. trained trees



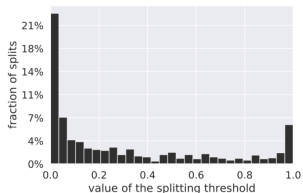
MNIST 2-6: robust trees



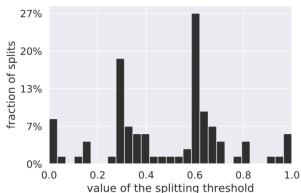
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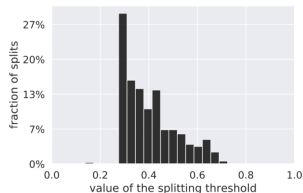
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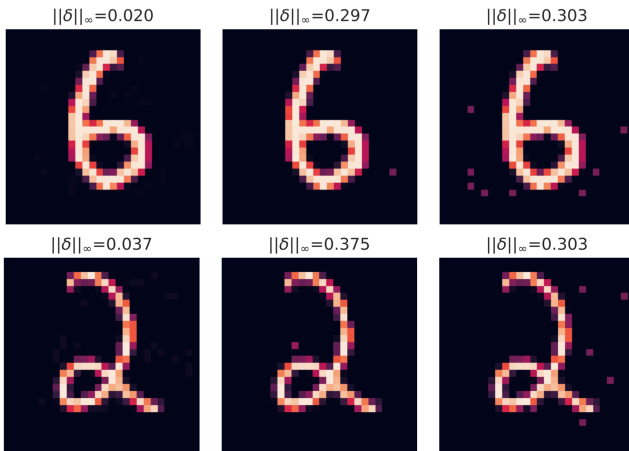


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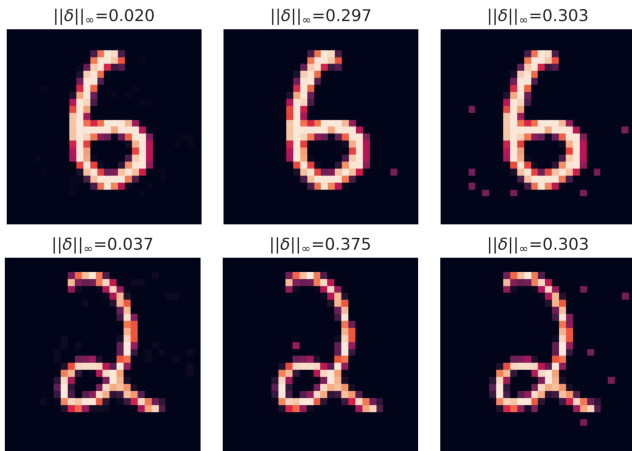
- Robust training changes the threshold distribution **dramatically!**
- Adversarial training also changes it, **but still has non-robust splits**

Adversarial examples for boosted trees



- **Models:** normal, adversarially trained, our robust boosted trees.

Adversarial examples for boosted trees



- **Models:** normal, adversarially trained, our robust boosted trees.
- Adversarial training leads to examples with $\|\delta\|_\infty < 0.3$
- **Our method** consistently leads to $\|\delta\|_\infty \geq 0.3$

Conclusions and outlook

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- **Tabular data** matters and it is ubiquitous. Real applications of L_p -robustness are rather there.
- **Robust and interpretable models are needed!**

Thanks for your attention! Questions?